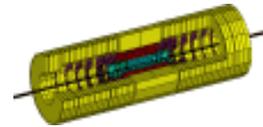




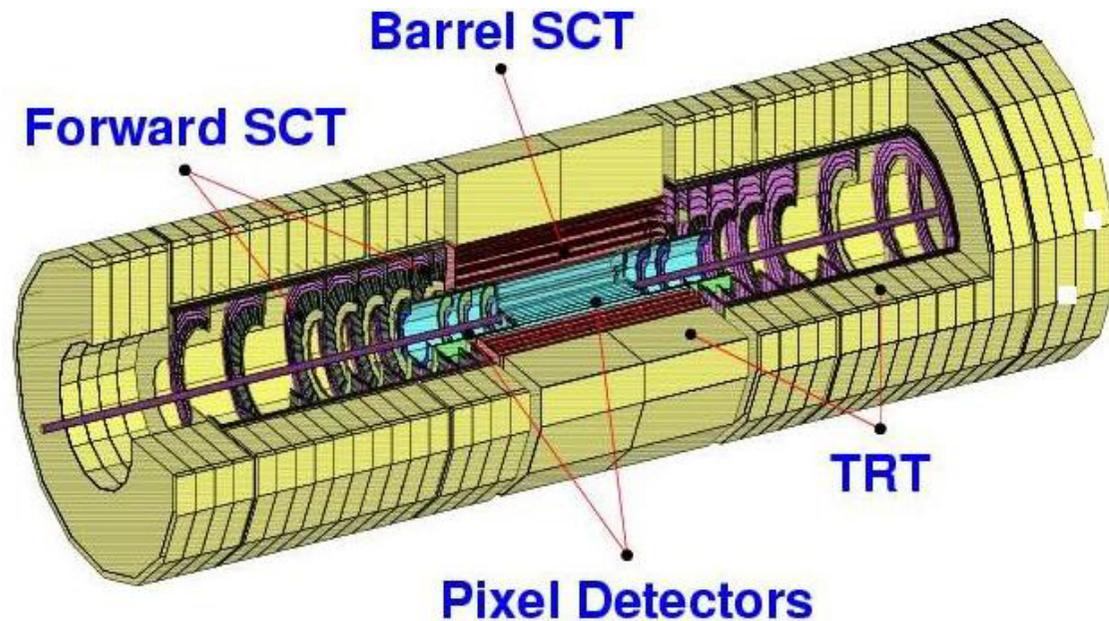
# ATLAS inner detector and flavour tagging



**Richard Hawkings (CERN)**

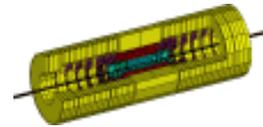
**LHC physics and detectors symposium, 1/5/03**

- Overview of ATLAS inner detector
  - Challenges for tracking at LHC
  - ATLAS ID design, recent changes
  - Initial layout without staged items
- Status of detector construction
  - Subdetectors and integration
- Performance of the detector
  - Alignment and calibration
  - Software evolution
  - Flavour tagging:  $b$ ,  $\tau$
- Conclusion





# Tracking at LHC

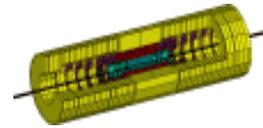


- Challenges for LHC tracking detectors
  - Occupancy: around 700 tracks within acceptance ( $|\eta| < 2.5$ ) per high lumi event
  - Time between bunch crossing: 25 ns – need very fast response/electronics
  - Radiation damage: fluence from  $10^{13}$ - $10^{14}$  equiv. 1 MeV neutrons/cm<sup>2</sup>/year
  - Material: minimise to avoid compromising calorimeter performance for e.g.  $H \rightarrow \gamma\gamma$ 
    - Limited space ( $r < 1.1$  m) – keep costs of solenoid and calorimeter under control
- ATLAS solution based on three technologies
  - Mixture of space point and continuous tracking – for resolution and pat.rec.
  - Pixel detector
    - 3 barrel layers, 3 endcap disks: 12  $\mu\text{m}$  r- $\phi$  and 60  $\mu\text{m}$  r-z resolution
  - Semiconductor Tracker (SCT)
    - Large area (60 m<sup>2</sup>) silicon detector: 4 barrels and 9 disks in each endcap
    - Four points per track, 16  $\mu\text{m}$  r- $\phi$  and 580  $\mu\text{m}$  r-z resolution (40 mrad stereo)
  - Transition radiation tracker (TRT)
    - Straw tube detector (axial barrel/radial endcap); 4mm diameter straws;  $r \sim 50$ -105 cm
    - Electron ID through detection of transition radiation photons

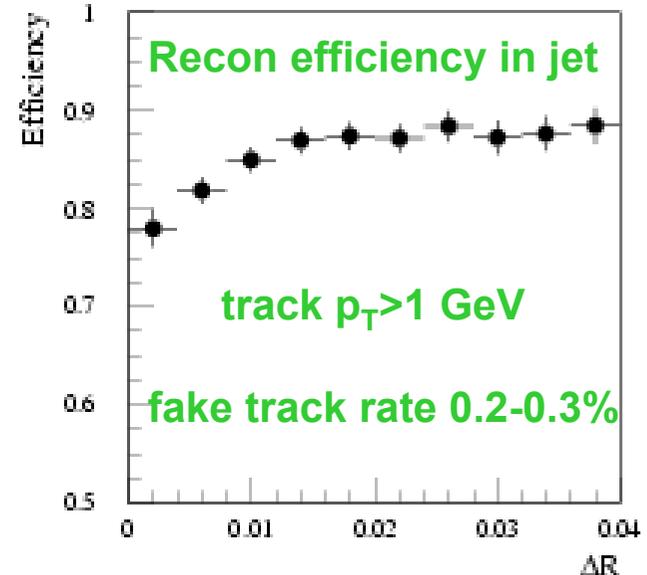
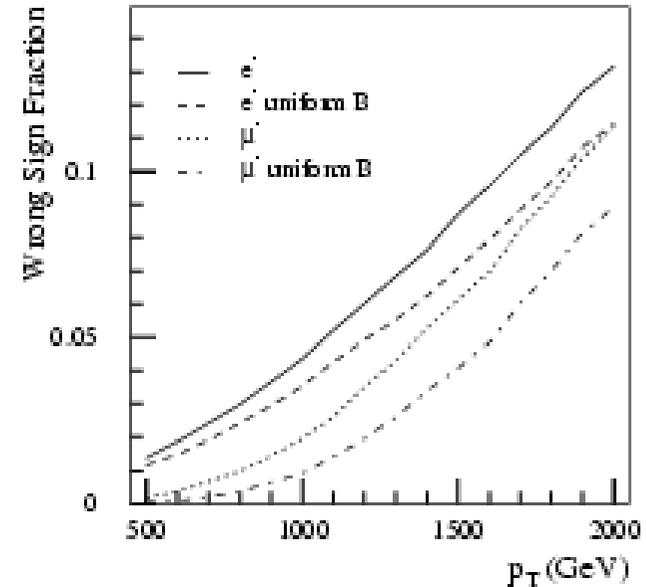




# Key design parameters

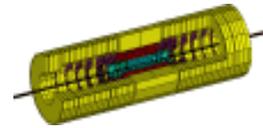


- ID inside barrel cryostat including solenoid and LAr calorimeter
  - 2T solenoid field, non uniform at high z
    - Reduces to 1.0T at  $z=2.7\text{m}$
  - $p_T$  resolution: charge det. at  $\sim 500\text{ GeV}$
  - Full coverage to  $|\eta|=2.5$  for all detectors
- Pattern recognition inside jets / with pileup
  - Challenging: high track density
  - 7 precision points/track (3 pixel+4 SCT)
    - Each  $r-\phi$  and  $z$  (40 mrad stereo in SCT)
  - Up to 36 TRT straw hits
    - Continuous tracking... optimised for tracking performance not TR e-ID
    - $\pi$  rejection up to 100 for 80% e-ID efi.
  - $\cot\theta$  resl.  $<10^{-3}$ ,  $V^0$  finding, b-tagging
  - Results from Physics TDR (1999)
    - Reference for ID performance

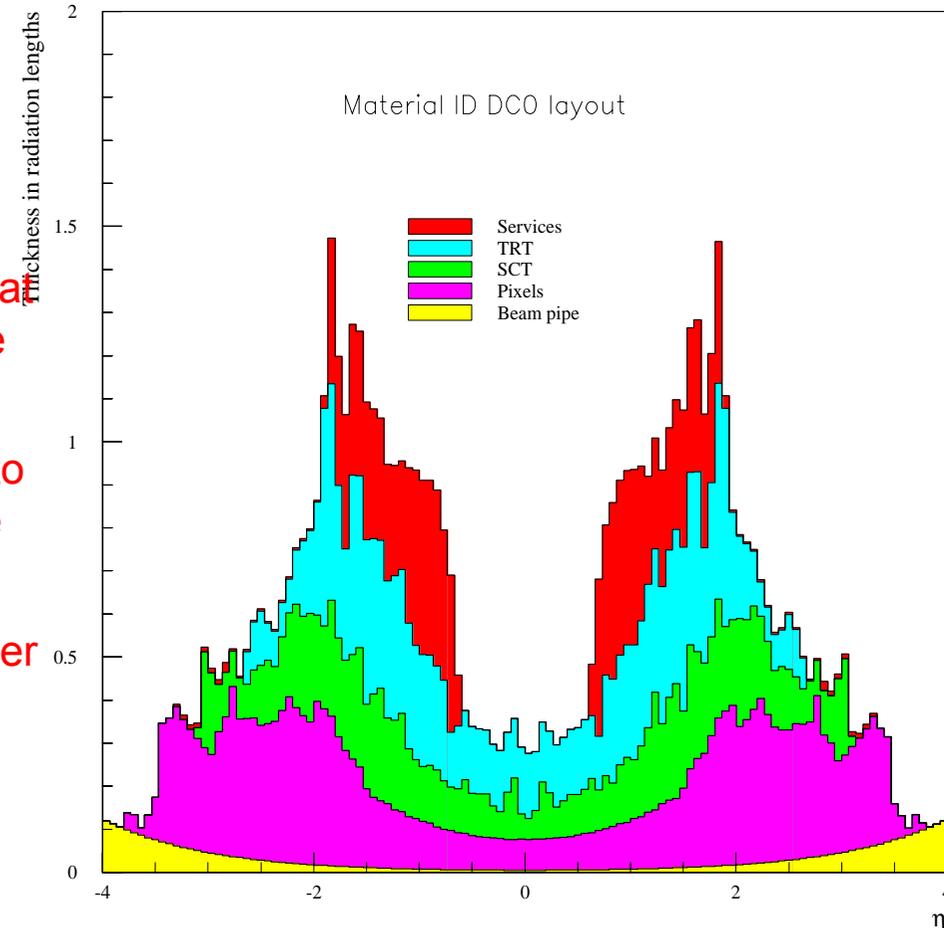




# Recent design changes



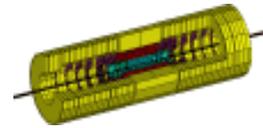
- Main changes are to pixel detector
  - Fully insertable layout
    - Pixels can be installed (and upgraded) without disturbing rest of ID
    - All pixel services run inside SCT endcap at low radius – mostly outside  $\eta$  acceptance
  - Change in detector radii
    - 1<sup>st</sup> pixel layer ('B layer') moved from 4.3 to 5.0 cm to accommodate larger beampipe
  - Change in pixel material
    - Factor 1.5 increase per layer due to thicker sensors, full engineering module design
- Lots of detailed engineering changes to SCT and TRT
  - Realistic services, connectors, thermal enclosures, patch panels...
    - An ongoing process as detectors go into production – still some updates to do



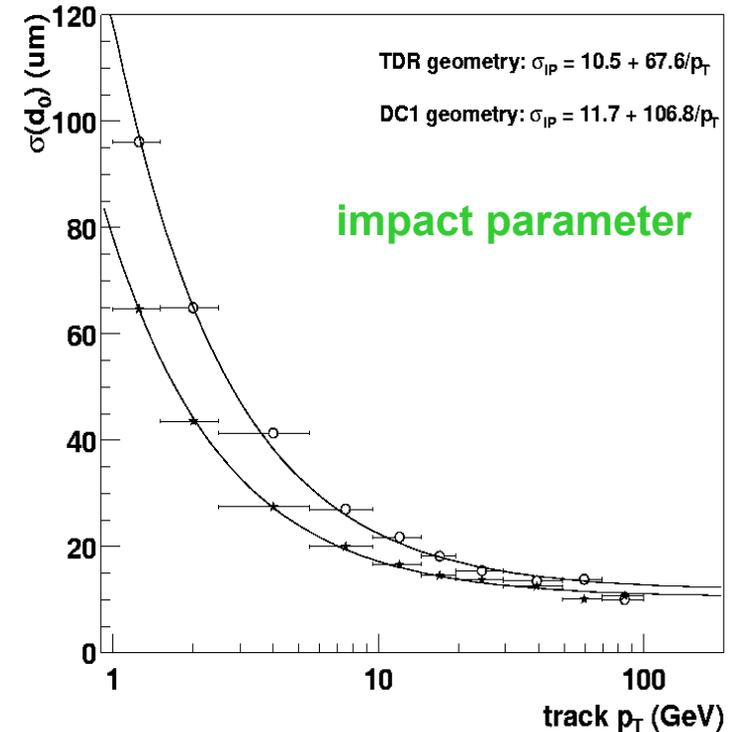
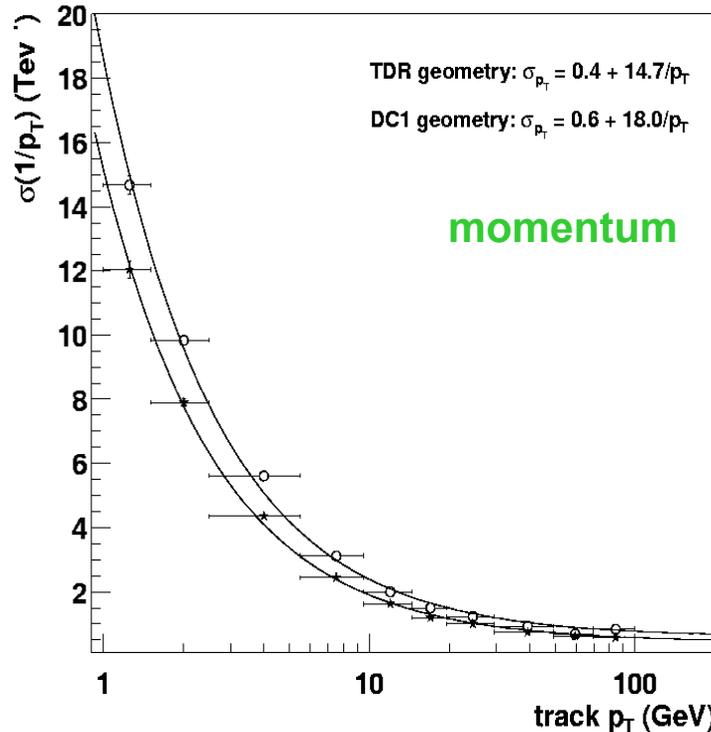
- At  $\eta=0$ , have  $0.3 X_0$ , rising to around  $1 X_0$  in detectors at  $|\eta|=2$
- Services all at high radius – little impact



# Effect of design changes



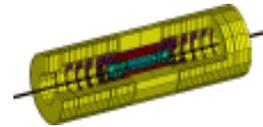
- Most visible in the transverse momentum and impact parameter resolution



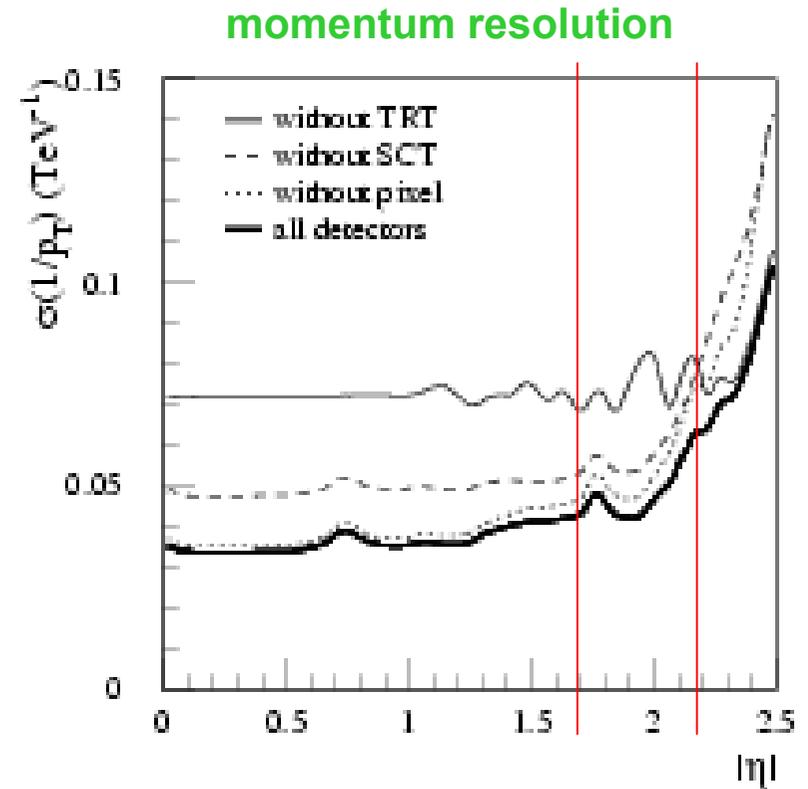
- Momentum and IP multiple scattering terms increase by 1.2 and 1.6 at  $\eta=0$ 
  - Effect of increased material and larger radius of first layer
  - Some impact on physics performance – see later ...



# Initial layout without staged items

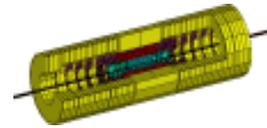


- Initial detector layout will not have:
  - Middle pixel barrel layer ( $r=9$  cm)
    - But B-layer is still there
  - Middle pixel disk ( $z=58$  cm)
  - TRT C wheels (acceptance  $1.7 < \eta < 2.5$ )
- Effect on:
  - b-tagging performance
    - ~25% reduction in light quark rejection
  - Momentum resolution
    - Around 50% worse in high  $\eta$  region
  - Pattern recognition capability
    - Difficult to quantify, but occurs for initial low luminosity running where patrec is easiest
- Physics impact:
  - 15-20% more luminosity for 'initial discoveries'
  - Full detector needed for high-lumi running



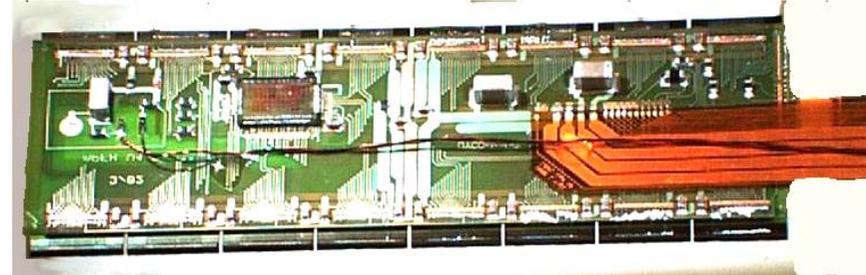


# Detector status - pixels

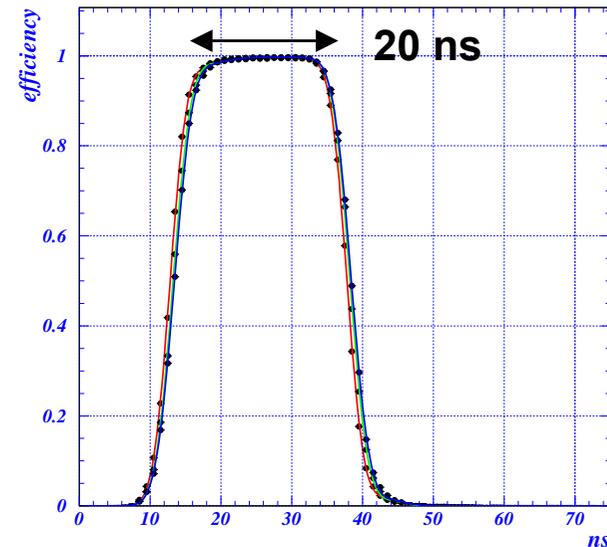


- Last subdetector to be installed
  - Pixel sensors and mechanics in production
  - Electronics (DSM) in last design iterations
    - Pilot production runs – use for first ‘final’ modules to gain time and experience
    - Integration of several chips + flex circuit onto one module shows good performance
- Tests with irradiated modules ( $10^{15}$  n/cm<sup>2</sup>)
  - Uniform behaviour – efficiency > 99%
    - Low timing dispersion between pixels
  - Low noise - <  $10^{-7}$  noise hit / pixel after irradiation – 10 hits in whole ATLAS pixels
- Next steps
  - Big effort on irradiation, system test and beam test of modules this year
    - Produce 2-300 modules this year (10-15%)
    - Production debugging, QA, tests ⇒ disks

Pixel module



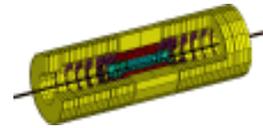
Efficiency vs  $t_0$  in testbeam







# Detector status - TRT

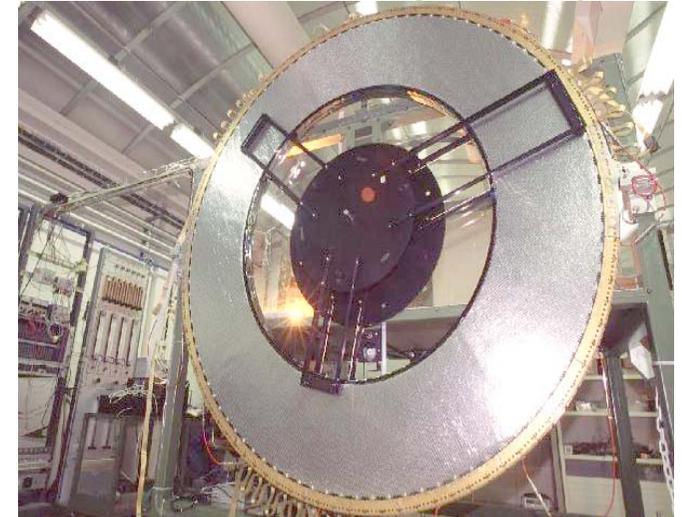


- Progress with components:
  - Straw production finished
  - Electronics – digital chip switched to DSM technology – in production
    - Some delays on analogue FE chips
- Module production and gas studies
  - Problem with barrel wire joint: delay stringing
    - Reassess active gas:  $\Rightarrow 70\% \text{Xe} + 27\% \text{CO}_2 + 3\% \text{O}_2$
    - Many tests of new gas – TRT performance is not significantly changed
    - New concept of ‘cleaning runs’ (with collisions) – ~1 day with ~10%  $\text{CF}_4$  to remove Si deposits on wires. Tracking but no TR.
    - Wire stringing now continuing
  - Endcap wheels – first delivered to CERN
    - Now starting up series production in Russia
  - Start to assemble barrel modules and stack endcap wheels at CERN in next year ...

## Barrel module production

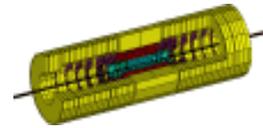


## Endcap wheel wire geometry test

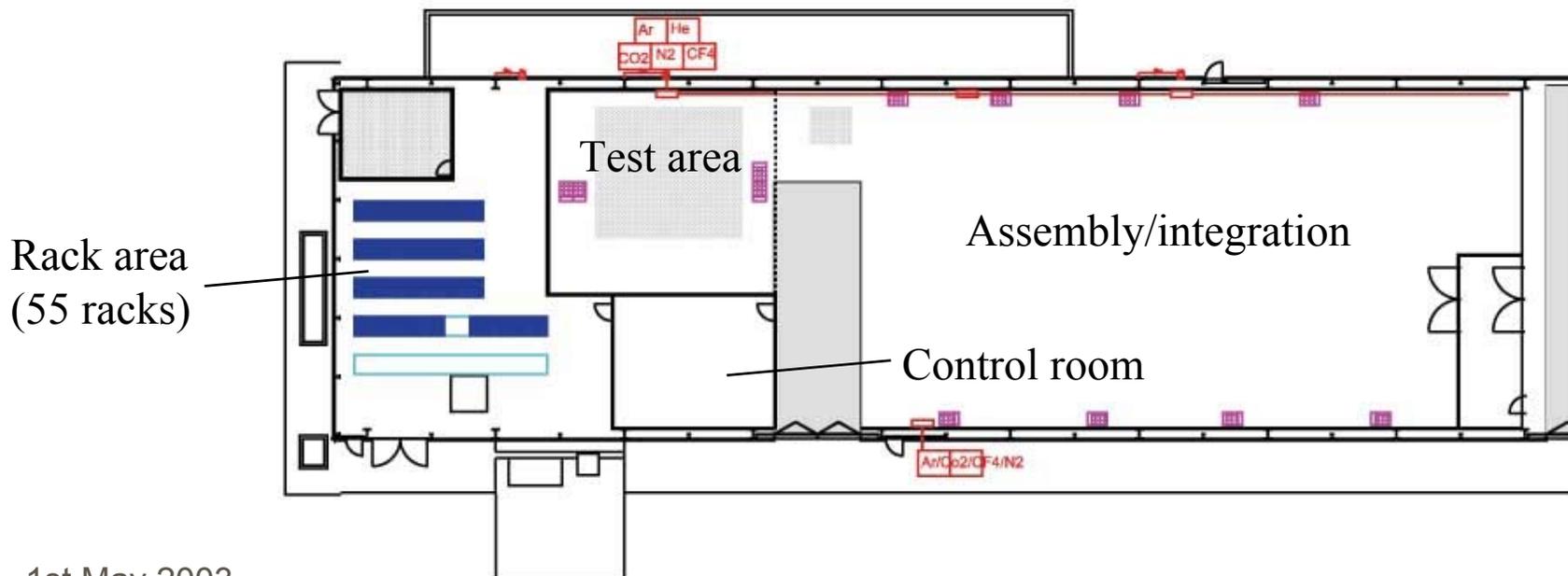




# Putting it together

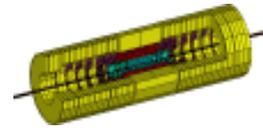


- ID components beginning to come together at CERN
  - Setting up dedicated facility at ATLAS pit for integration and assembly
    - SCT 4-barrel integration, TRT barrel assembly and endcap 'stacking'
    - SCT-TRT integration and testing (separate and combined)
    - Pixel detector assembly (together with beampipe)
  - Significant infrastructure (moderate cleanroom, cooling, DAQ, DCS...)
    - Preparation of building/infrastructure being finalised – first detector pieces 2<sup>nd</sup> half 2003

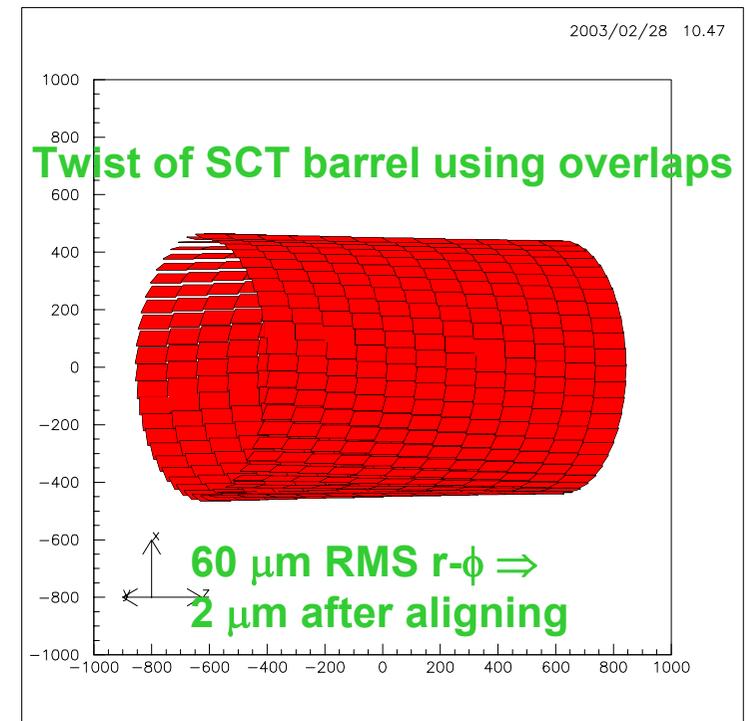




# Alignment and calibration

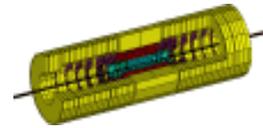


- Unprecedented requirements for alignment and calibration of ATLAS ID:
  - For most physics,  $7\mu\text{m}$  (pixel),  $12\mu\text{m}$  (SCT),  $\sim 30\mu\text{m}$  (TRT) r- $\phi$  alignment required
    - On scales over  $O(1\text{m})$ , with 10s of kW of heat load... challenging
  - For precision physics (e.g. 15 MeV W mass measurement), need r- $\phi$  at  $1\mu\text{m}$  level
  - B-field needs to be understood to 0.05% – combination of field mapping and fitting
- Strategies for alignment:
  - Precision mechanics and optical surveys
    - At many stages in construction and assembly
  - Pre-installation X-ray survey of SCT (and TRT?)
    - Locate modules to  $10\mu\text{m}$  r- $\phi$ ,  $50\mu\text{m}$  z precision
  - Alignment with tracks during running
    - Exploit overlaps and 'normal' tracks (e.g. W, b $\rightarrow\mu$ )
    - Potential to solve for whole SCT+pixels (6 d.o.f./ module) and all TRT straws (alignment plus R-t calibration) in few hours data taking + processing
  - FSI – in-situ laser-based interferometry for SCT
    - Monitor distortions of SCT structures in real time





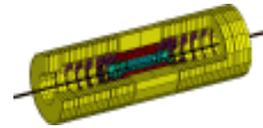
# Software and performance



- Two major pattern recognition and trackfitting programs:
  - xKalman – Kalman filter based approach, seeded from TRT or SCT/pixels
  - iPatRec – combinatoric space point search in SCT/pixels, extrapolate to TRT
    - Similar results on simulated data – best final approach will depend on real-life detector performance.
    - Mixed Fortran/C++ versions used for PhysicsTDR, now major effort in migrating to OO analysis framework (Athena) and common elements where possible.
  - Major effort on ‘event data model’ for inner detector
    - Flow of information: digitisation  $\Rightarrow$  ‘byte stream’ data  $\Rightarrow$  clusters  $\Rightarrow$  space points  $\Rightarrow$  tracks
    - Work starting on including proper alignment and calibration information in chain.
- Data challenges:
  - Simulating and reconstructing ATLAS events is a major operation
    - Data challenges DC0/DC1 – 1000s CPUs used for weeks, worldwide – starting to use GRID-type tools.
    - DC1 data used for following performance studies – compare with old PhysTDR results
    - So far, results without pileup (additional minimum bias events) – later phase of DC1



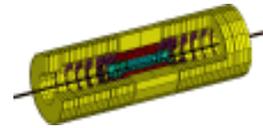
# Flavour tagging - introduction



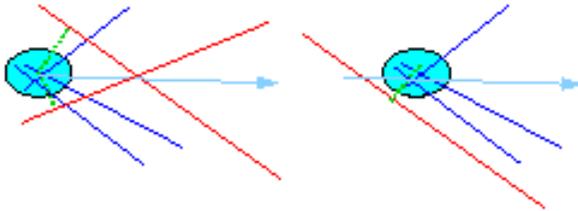
- Flavour tagging studies concentrated on b-jets:
  - Top quark decays:  $t \rightarrow bW$  – essential tool for study of top physics
  - Objects coupling preferentially to heavy particles, e.g. Higgs bosons
    - Important for many discovery channels at both low and high luminosity
- Main focus on b-tagging using long lifetime and high mass of b hadrons
  - Tracks with large impact parameters w.r.t. primary vertex, secondary vertices
    - Also some tagging power from  $b \rightarrow l$  decays – soft electrons, or muons in TileCal
  - Simple and fast b-tagging algorithms in level 2 trigger and event filter
- Properties of b-jets of interest:
  - Wide momentum range, from 15 GeV to 400 GeV (range of Higgs masses)
    - Multiple scattering dominates at low jet energies, pattern recognition at high energies
  - Typically define jets with a cone size of  $\Delta R=0.4$ 
    - Catches nearly all b decay products, charged track multiplicity 5-10 for  $p_T > 1$  GeV, around half from b decay, others from fragmentation.
    - Particles from minimum bias relatively unimportant (in pp), especially at low luminosity
- Recent work: performance with latest layouts, algorithmic improvements



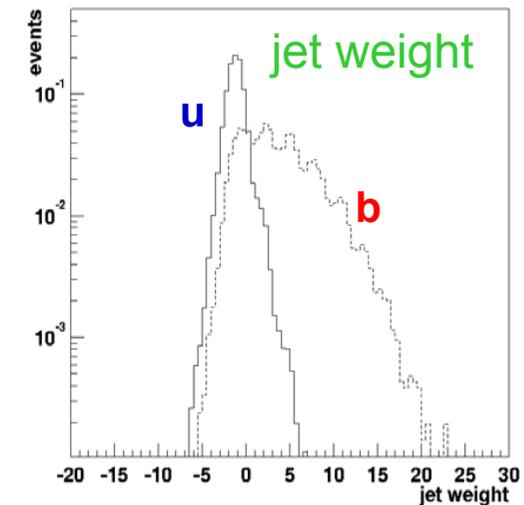
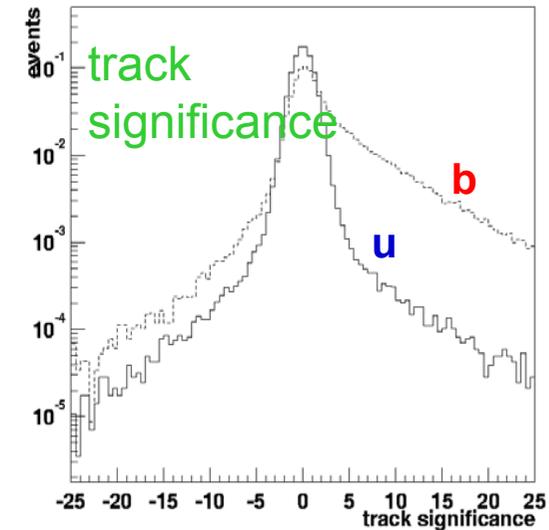
# b-tagging – basic method



- Main b-tagging algorithms based on **impact parameter significance  $S$** 
  - Look at transverse IP relative to beamspot position, divided by error
  - Sign according to direction of nearest jet

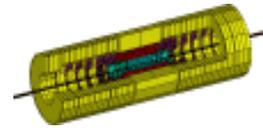


- Transform into a ratios of probabilities for tracks of significance  $S$  from light and  $b$  jets
- Combine the probabilities for all tracks into a jet weight.
  - Simple in transverse plane, as beamspot is small ( $15 \mu\text{m}$ ) and stable.
  - If primary vertex of interaction can be reconstructed (resolution around  $30 \mu\text{m}$ ), can also use  $z$  coordinate info ('2D+z' / '3D')





# b-tagging performance I



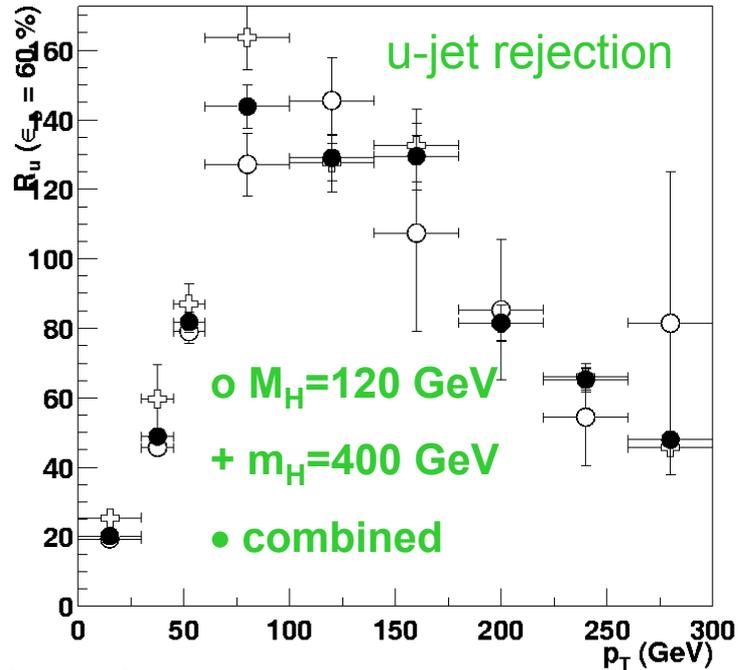
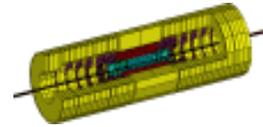
- Study performance on WH events for  $m_H=120$  and 400 GeV
  - Force H to decay to heavy ( $b\bar{b}$ ) and light ( $u\bar{u}, c\bar{c}$ ) jets to calculate rejection factors
  - Compare PhysTDR performance with DC1 layout using 2D and '3D' b-tagging:
    - For 50% b-jet tagging efficiency, look at rejection factors for u and c jets

u/c rejection	PhysTDR	DC1 (2D)	DC1 (2D+z)
$R_u(120 \text{ GeV})$	$359\pm 23$	$189\pm 8$	$321\pm 14$
$R_u(400 \text{ GeV})$	$141\pm 9$	$144\pm 8$	$195\pm 9$
$R_c(120 \text{ GeV})$	$11.5\pm 0.4$	$9.8\pm 0.1$	$12.3\pm 0.2$
$R_c(400 \text{ GeV})$	$13.6\pm 0.5$	$10.6\pm 0.2$	$12.6\pm 0.3$

- Significant deterioration in performance for low energy jets ( $m_H=120$  GeV)
  - Low  $p_T$  tracks – multiple scattering and material important
  - Less significant for high energy u and for charm jets – improvements in pattern recognition – less tails in IP distributions
- Including z information improves things, recovers at least PhysTDR performance

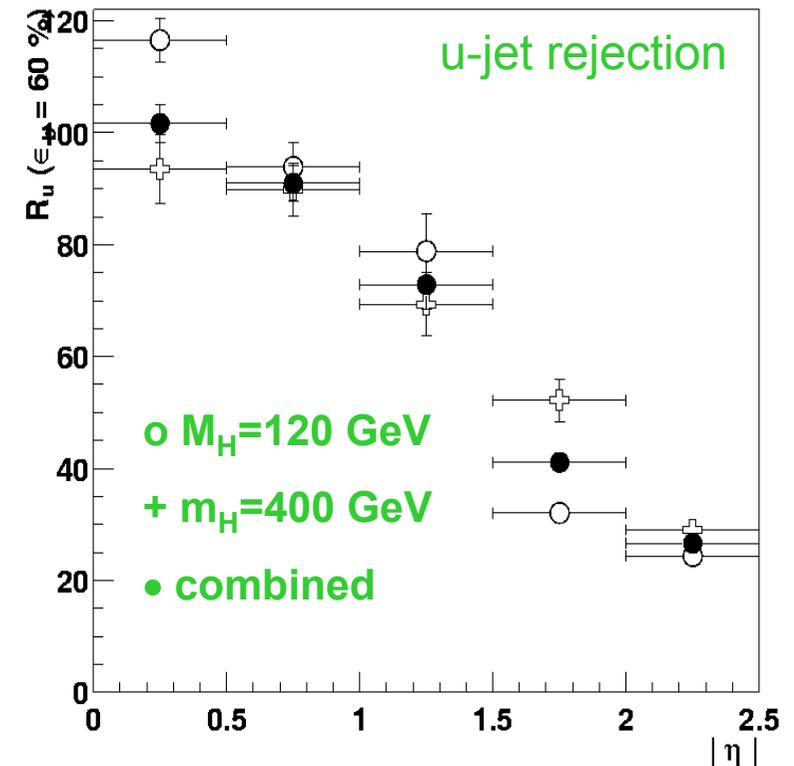


# b tagging performance - II



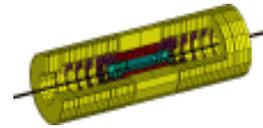
- Significant dependence on jet  $p_T$ :
  - Balance between multiple scattering (low  $p_T$ ) and pattern recognition effects (high  $p_T$ )
    - Very dense jets at high energy
    - Best rejection around 100 GeV
    - Little intrinsic dependence on boson mass

- Significant dependence on  $\eta$ :
  - Tracking performance degrades at high  $\eta$ , and jet energy rises for constant  $E_T$

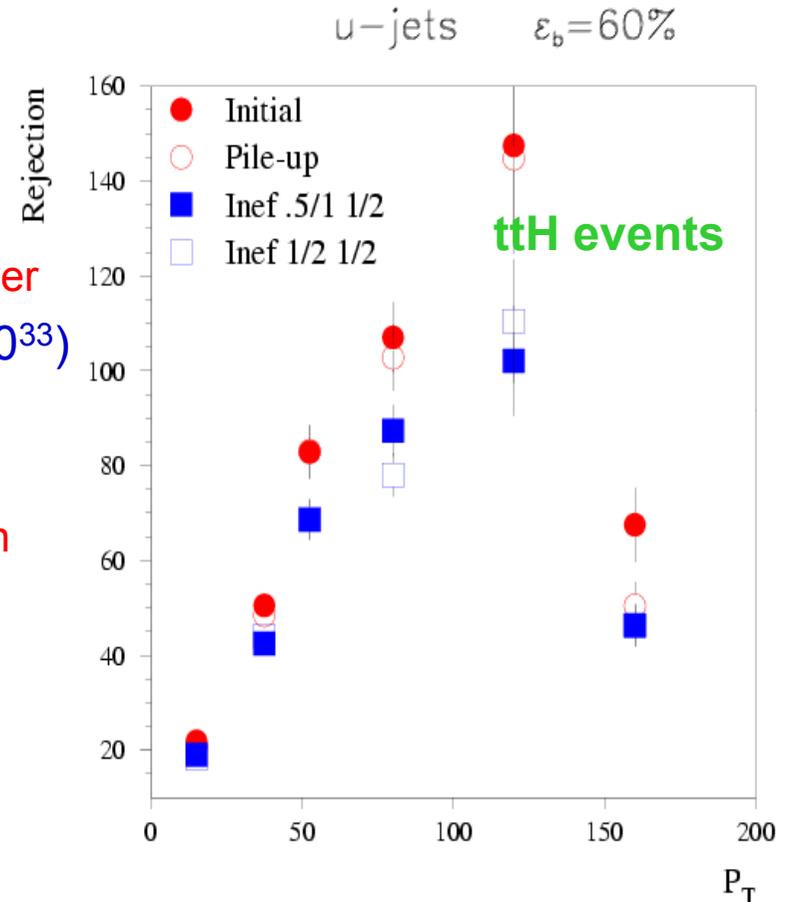




# Study of $t\bar{t}H$ events

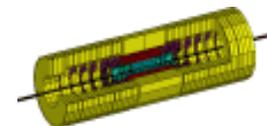


- More studies on  $t\bar{t}H$  events:
  - Compared to WH, additional jets from t decays
    - ~20% rejection loss due to jet overlaps
    - Similar performance on b-jets from t and H
  - Effect of switching to 400  $\mu\text{m}$  pixels in b layer
    - Around 10% degradation, but some may be recovered by choosing 'best' modules for b layer
  - Effect of low-lumi pileup (4.6 min-bias @  $2 \times 10^{33}$ )
    - Small – dominated track density from jet
  - Effect of initial 2-pixel layer layout
    - Worse IP resolution – around 30% degradation
  - Program of work to parameterise performance with new layout for fast simulations
- Calibration of b-tagging:
  - Use  $t\bar{t} \rightarrow Wb W\bar{b} \rightarrow q\bar{q}b l\nu\bar{b}$  events
    - Select using b-tag + lepton ID from one top
    - Kinematic fit ( $m_{\text{top}}$ ) on  $q\bar{q}b$  system to ID b/u jets

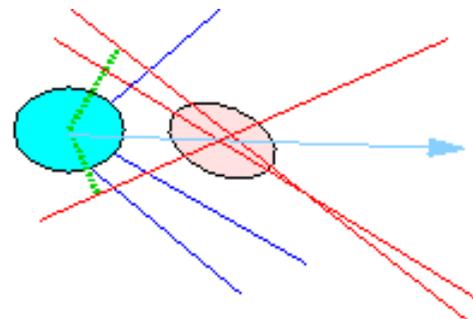




# Algorithm improvements



- Impact parameter method does not use all information:
  - Secondary vertex reconstruction
  - Vertex mass information
    - Important to get best performance at LEP and SLD, especially for c tagging
- First studies of secondary vertex recon.
  - Kalman filter-based fast vertex finding
  - Identify primary and all 2-track secondary vertices.
    - Merge secondaries to make b vertex
    - Vertex in 70% / 8% of b/u jets
  - Two discriminating variables:
    - Mass of b decay vertex
    - $E_{\text{vertex}}/E_{\text{jet}}$  – fraction of jet energy in vertex
  - Combine variables with IP-based tag

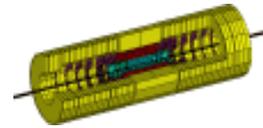


u rejection	2D+z	2D+z+vtx
<b>3 pixel layers</b>		
$R_u(100 \text{ GeV})$	430±53	751±125
$R_u(400 \text{ GeV})$	293±26	606±78
<b>2 pixel layers</b>		
$R_u(100 \text{ GeV})$	219±19	361±41
$R_u(400 \text{ GeV})$	198±15	351±34

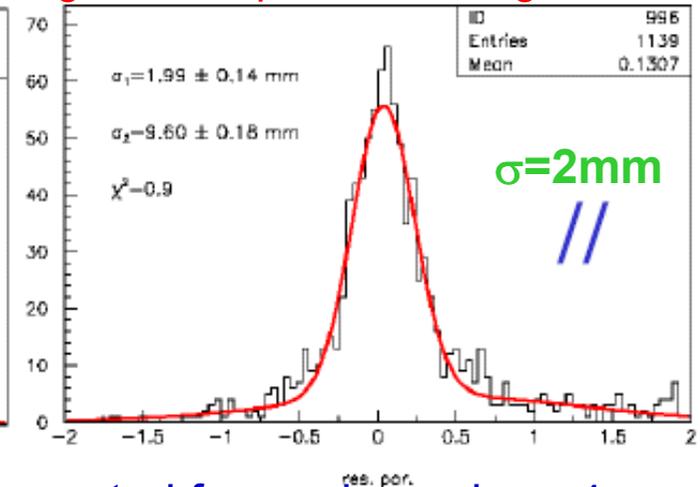
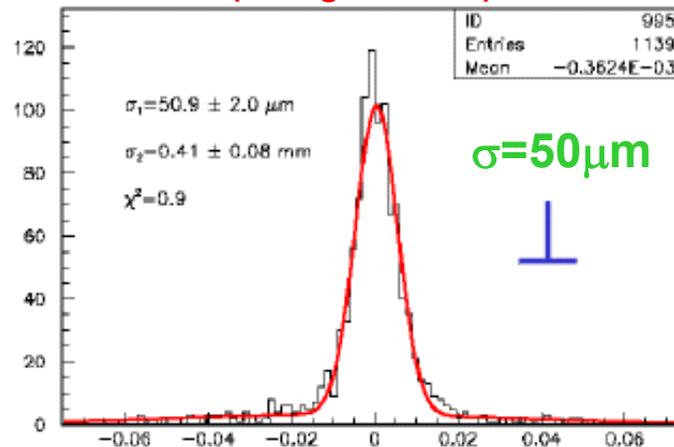
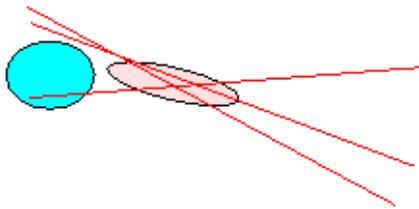
- Factor 1.5-2 improvement in rejection, even for reduced 2-layer detector
  - Encouraging....



# $\tau$ tagging



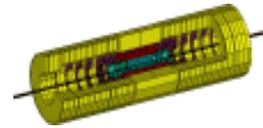
- $\tau$  tagging useful in e.g.  $A/H \rightarrow \tau\tau$ , usually in mixed leptonic/hadronic mode
  - Main selection tools are lepton ID and  $E_{\text{miss}}^T$ , rather than vertex selections
  - $\tau$  decays in very narrow cones, usually 1 or 3 charged particles – challenging
    - Small impact parameters, low multiplicity vertices with small opening angle
  - Some study of reconstructing secondary vertices in 3 prong hadronic  $\tau$  decays
    - Look at resolution on 3 prong vertex position orthogonal and parallel to  $\tau$  flight direction



- Cuts include requirement for 3-prong vertex separated from primary by  $> 4\text{mm}$
- Gives efficiency of 44%, QCD-jet rejection of  $> 10^3$  for 3 prong decays
  - Provides a modest (10%) enrichment of  $A \rightarrow \tau\tau$  sample



# Conclusions - the road ahead



- ATLAS inner detector design is now mature
  - Last phases of detailed engineering design ongoing
    - Services, patch panels, off detector components, integration
  - Initial layout without staged items
    - Moderate loss in performance – but need full detector for high luminosity
  - Most components now in production, and assembly is beginning
    - Some problems found (inevitable in such a large complex system), solutions being worked on and production proceeding.
  - Major work ahead on integration of ID parts coming to CERN, installation and commissioning – preparations are beginning
- Work continues on software and performance
  - Follow changes in engineering design and software evolution
  - Studies of alignment and calibration, for 'day 1' and ultimate performance
  - Performance is being maintained to meet ATLAS physics goals
    - Performance of detector is robust
    - New ideas – e.g. b-tagging with secondary vertices, use of  $\tau$  tagging, heavy ions
- Look forward to exploiting the ATLAS ID for physics beginning in 2007